

#### **Features**

- High-C<sub>AB</sub>-Loading driving ability
- Polarity Free for RS485 bus pins
- Integrated TVS Protection for Bus Terminals:
   ±15 kV IEC 61000-4-2, Contact Discharge
   ±20 kV IEC 61000-4-2, Air-Gap Discharge
- HBM/MM ±8kV / ±800V ESD Specification for all pins
- Meet the Requirements of the EIA/TIA-485
   Standards with 5V Power Supply
- Data Rate up to 10Mbps
- Hot-Swap Glitch free Protection on Control Inputs
- Up to 256 Transceivers on the Bus

#### **Applications**

- Energy Meter Networks
- Motor Control
- Industrial Control
- Telecommunications Equipment
- Security System

## Description

The AZRS5485E is a *High-C<sub>AB</sub>-Loading driving* and *Polarity-Free* half-duplex RS485 transceiver IC with ±15kV IEC 61000-4-2 contact discharge protection. This device is fully compliant with the EIA/TIA-485 standard with 5V power supply.

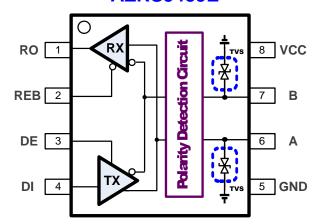
For the *Polarity-free* function, the AZRS5485E can automatically detect the polarity for A and B pins when "pull-high" for A and "pull-low" for B have been designed on the RS485 bus. The polarity detection function will be enabled when the AZRS5485E has been power up to 5V.

The detection function real-time monitors the bus polarity without any data flow on the RS485 bus. AZRS5485E is slave-type RS485 to feature the Polarity-Free function, which does not design the pull-up and pull-down resistor on the slave device.

For the *High-C<sub>AB</sub>-Loading* condition, there are capacitors between bus A and bus B when long bus condition or protected device connected. AZRS5485E can enhance the bus voltage quickly to balance the voltage of bus A and bus B so that they can transmit the data on the long cable length under the same application.

The AZRS5485E has the thermal shutdown and the current limited function in the transmitter to protect the device from damage by system fault conditions during normal operating condition. AZRS5485E is designed 1/8 unit load with minimum  $96k\Omega$  of input impedance, which can connect 256 devices on a bus at least.

#### AZRS5485E



**Functional Block of AZRS5485E** 

Part Number	Duplex	Tx/Rx	Supply	Data Rate	HBM/MM	IEC 61000-4-2	Special Function	Package
				(Mbps)		Contact on A,B		Type
AZRS5485E	Half	1/1	5V	10	±8kV/800V	± 15kV	Polarity Free	SO-8
							High-C <sub>AB</sub> driving	

# **ABSOLUTE MAXIMUM RATINGS**

PARAMETER	PARAMETER	RATING	UNITS
Power Supply Vcc	Vcc	-0.3 to 8.0	V
Control Input Voltage	REB, DE	-0.3 to (Vcc+ 0.3)	V
Receiver Input Voltage	A, B	±13	V
Receiver Output Voltage	RO	-0.3 to (Vcc+ 0.3)	V
Transmitter Output Voltage	A, B	±13	V
Transmitter Input	DI	-0.3 to (Vcc+ 0.3)	V
Operating Temperature	T <sub>OP</sub>	-40 to +85	°C
Storage Temperature	T <sub>STO</sub>	-65 to +150	°C

#### DC ELECTRICAL CHARACTERISTICS

(Vcc=5V  $\pm$ 5% with T<sub>AMB</sub>= T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at Vcc=5V and T<sub>AMB</sub>= 25 °C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Transmitter							
Differential Transmitter Output	V <sub>OD1</sub>	No load				Vcc	V
Differential Transmitter Output	V <sub>OD2</sub>	Fig.1, $R_L = 27\Omega$		1.5			V
Change in Magnitude of Differential Output Voltage	$\Delta V_{OD}$	Fig.1, $R_L = 27\Omega$				0.2	V
Transmitter Common- Mode Output Voltage	V <sub>oc</sub>	Fig.1, R <sub>L</sub> = 27Ω				3.5	V
Change in Magnitude of Common- Mode Voltage	ΔV <sub>oc</sub>	Fig.1, $R_L = 27\Omega$				0.2	V
Input High Voltage	V <sub>IH</sub>	DE, DI, REB		2.0			V
Input Low Voltage	V <sub>IL</sub>	DE, DI, REB				0.8	V
Input Current	I <sub>IN1</sub>	DE, DI, REB				±2	μΑ
		DE=0V,	V <sub>IN</sub> =12V			125	
Input Current for A and B	I <sub>IN2</sub>	Vcc=0V or 5.25V	V <sub>IN</sub> =-7V			-75	μΑ
Transmitter Short-Circuit Output Current	I <sub>OSD</sub>	-7V ≤ V <sub>OUT</sub> ≤	12V	-250		250	mA
RECEIVER							
Receiver Differential Threshold Voltage	V <sub>TH</sub>			-100		+100	mV
Receiver Input Hysteresis	$\Delta V_{TH}$				20		mV
Receiver Output High Voltage	V <sub>OH</sub>	Io= -4mA, VID= 200mV		Vcc-1.5			V
Receiver Output Low Voltage	V <sub>OL</sub>	Io= 4mA, VID= -				0.4	V
Three- State Output Current at	I <sub>OZR</sub>	$0.4V \leq V_{CM} \leq$	2.4V			±1	μA

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
RECEIVER							
Receiver Input Resistance	R <sub>IN</sub>	-7V ≤ V <sub>CM</sub> ≤	≨ +12V	96			kΩ
Receiver Output Short-Circuit Current	I <sub>OSR</sub>	Fig. 6, 0V $\leq$ V <sub>RO</sub> $\leq$ Vcc		±7		±95	m A
SUPPLY CURRENT							
Supply Current	Icc	No load, REB=GND,	DE= Vcc		500	900	μΑ
ouppiy ourient		Dl=Vccor GND.	DE= GND		400	800	μΑ

## **SWITCHING CHARACTERISTICS**

(Vcc=5V  $\pm$ 5% with T<sub>AMB</sub>= T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at Vcc=5V and T<sub>AMB</sub>= 25 °C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Transmitter Input to Output	t <sub>DPLH</sub> , t <sub>DPHL</sub>	Fig.2 and 7, $R_{\text{DIFF}}$ =54 $\Omega$ , $C_{\text{L1}}$ = $C_{\text{L2}}$ = 100pF	5	8	15	ns
Transmitter Output Skew $\left t_{DPLH}-t_{DPHL}\right $	t <sub>DSKEW</sub>	Fig.2, Fig.7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF		5	10	ns
Transmitter Rise or Fall Time	t <sub>DF</sub> , t <sub>DR</sub>	Fig.2, Fig.7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF		7		ns
Data Rate	f <sub>Data</sub>				10	Mbps
Transmitter Enable to Output Low	t <sub>DZL</sub>	Fig.4, Fig.8, C <sub>DL</sub> = 100pF, S1 closed			70	ns
Transmitter Enable to Output High	t <sub>DZH</sub>	Fig.4, Fig.8, C <sub>DL</sub> = 100pF, S2 closed			70	ns
Transmitter Disable Time from Low	t <sub>DLZ</sub>	Fig.4, Fig.8, C <sub>DL</sub> = 15pF, S1 closed			70	ns
Transmitter Disable Time from High	t <sub>DHZ</sub>	Fig.4, Fig.8, C <sub>DL</sub> = 15pF, S2 closed			70	ns
Receiver Input to Output	t <sub>RPLH</sub> , t <sub>RPHL</sub>	Fig.5, Fig.9, $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15$ ns	20	105	150	ns
$\left t_{RPLH}-t_{RPHL}\right $ Different Receiver Skew	t <sub>RSKD</sub>	Fig.5, Fig.9, $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15$ ns		6		ns
Receiver Enable to Output Low	t <sub>RZL</sub>	Fig.3, Fig.10, C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Enable to Output High	t <sub>RZH</sub>	Fig.3, Fig.10, C <sub>RL</sub> = 15pF, S2 closed		20	50	ns
Receiver Disable Time from Low	t <sub>RLZ</sub>	Fig.3, Fig.10, C <sub>RL</sub> = 15pF, S1 closed		20	50	ns
Receiver Disable Time from High	t <sub>RHZ</sub>	Fig.3, Fig.10, C <sub>RL</sub> = 15pF, S2 closed		20	50	ns

## PIN FUNCTION DESCRIPTION

Pin Number	Mnemonic	Function
1	RO	Receiver Output: When REB is low and if (A - B) ≥ +100mV,
		RO is high; if (A - B) ≤ -100mV, RO is low.
2	REB	Receiver Output Enable: REB is low to enable the Receiver; REB
		is high to disable the Receiver.
3	DE	Transmitter Output Enable: DE is high to enable the transmitter;
		DE is low to disable the transceiver.
4	DI	Transmitter Input: When DE is high, a low on DI forces A output
		low and B output high. Similarly, a high on DI forces A output high
		and B output low.
5	GND	Ground pin. Must be connected to 0V.
6	А	Non-inverting Receiver Input and Non-inverting Transmitter
		Output
		(Polarity Free design inside)
7	В	Inverting Receiver Input and Inverting Transmitter Output
		(Polarity Free design inside)
8	VCC	Power Supply Input 5V.

## **FUNCTION TABLE**

TRANSMITTING							
INPUTS OUTPUTS							
REB	DE	DI	Α	В			
Х	1	0	0	1			
X	1	1	1	0			
X	0	X	HIGH- Z	HIGH- Z			

X= Don't care HIGH- Z= High impedance

RECEIVING							
	INPUTS						
REB	DE	A - B	RO				
0	0	≥ +0.1 V	1				
0	0	≤-0.1 V	0				
0	0	Open/Shorted	1				
1	0	X	HIGH- Z				

X= Don't care HIGH- Z= High impedance



#### **Detail Description**

The AZRS5485E is a half-duplex RS-485 transceiver IC with IEC61000-4-2 contact ±15kV ESD protection for bus pins (A and B), which contains one transmitter and one receiver inside with 5V power supply. This device is fully compliant with the EIA/TIA-485 standard.

The AZRS5485E features the hot-swap glitch free design which guarantees the outputs of the transceiver in a high impedance state during the power-up period until the supply voltage has stabilized.

The AZRS5485E with whole chip ESD protected design for all of the I/O pins has robust ESD protection up to both HBM  $\pm 8$ kV and MM  $\pm 800$ V. Moreover, the latchup immunity of the AZRS5485E is up to  $\pm 400$ mA for all of the pins. For IC self discharge issue, the CDM protection level of the AZRS5485E is up to  $\pm 1$ kV.

#### **Transmitter**

The design of the transmitter is a non-inverted translator that converts the single-ended TTL input signal to differential EIA/TIA-485 signal level. The transmitter of the AZRS5485E guarantees 10Mbps data rate communication. When the transmitter is active (DE= HIGH), the single-end TTL input signals of transmitter will be transported to differential output RS485 signals of the transmitter. Under the disable state (DE= LOW), the outputs of transmitter keep at high impedance state.

The differential output voltage (VA-VB) of the AZRS5485E is 2.0V with  $54\Omega$  load under T=  $25^{\circ}$ C.

#### Receiver

The receiver of the AZRS5485E converts the differential EIA/TIA-485 signals to single-end output TTL signal when receiver is in active state (REB=LOW), which incorporates input filtering in addition to input hysteresis. The input filtering

enhances the noise immunity under normal operating condition. When the receiver is disable (REB=HIGH), the output of the receiver keeps in high impedance state no matter what the input of the receiver is.

#### **Advanced Fail-Safe**

The AZRS5485E guarantees a receiver output high when the receiver inputs are short, open, idle or wrong connection on the slave device, which is advanced fail-safe. The threshold voltage of receiver input is between -100mV and +100mV. If the differential input voltage (A - B) of receiver is greater than or equal to +100mV, receiver output (RO) is logic-high. If (A - B) is less than or equal to -100mV, RO is logic-low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage (A - B) is 0V, so the RO is logic-high at that time.

#### 1/8 Unit Load

The RS-485 standard defines both receiver inputs impedance are  $12k\Omega$  (1 unit load) and the maximum 32-unit loads on the bus. The AZRS5485E transceiver has a  $96k\Omega$  input impedance (1/8 unit load) of the receiver, allowing up to 256 or fewer devices to be connected in parallel on the RS485 bus.

#### **Transmitter Output Protection**

The AZRS5485E has the current limitation function and the thermal shutdown protection in the transmitter. Firstly, the function of current limitation provides immediate protection against short circuits over the whole common-mode voltage range (-7V to +12V). Secondly, the function of thermal shutdown protection forces the transmitter outputs into a high impedance state if the die temperature becomes excessive.



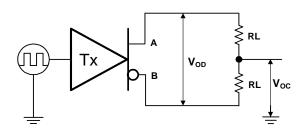


Fig.1 Transmitter DC test circuit

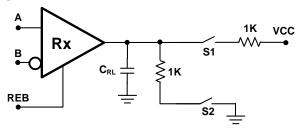


Fig.3 Receiver enable/disable timing test load

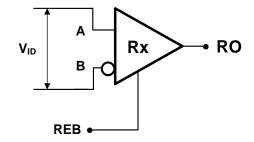


Fig.5 Receiver timing test circuit

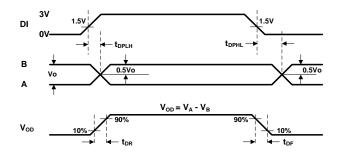


Fig.7 Transmitter Propagation Delays

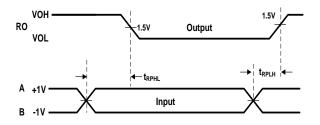


Fig.9 Receiver Propagation Delays

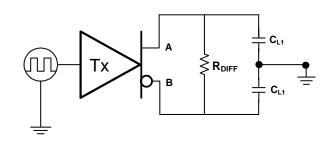


Fig.2 Transmitter timing test circuit

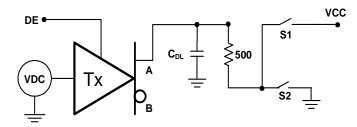


Fig.4 Transmitter enable/disable timing test load

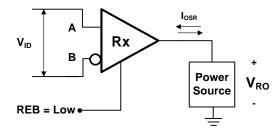


Fig.6 Receiver output short circuit

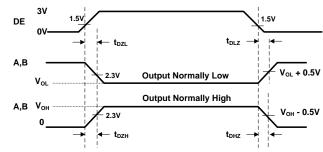


Fig.8 Transmitter Enable and Disable Times

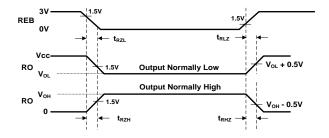


Fig.10 Receiver Enable and Disable Times

# High ESD-Protected RS485 Transceiver IC

#### SWITCHING CHARACTERISTICS for POLARITY FREE

(Vcc=5V  $\pm$ 5% with T<sub>AMB</sub>= T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at Vcc=5V and T<sub>AMB</sub>= 25 °C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Detection Time for Polarity Free		S1, S3 : ON ; S2, S4 : OFF				
	t <sub>DPF</sub>	S2, S4 : ON ; S1, S3 : OFF	50		350	ms
		Fig. 11 and Fig. 12				

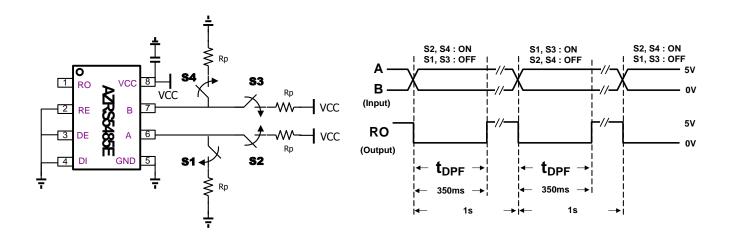


Fig. 11 Detection Time for Polarity Free testing Fig. 12 Input and Output timing for detection time for circuit polarity time

The detection time for polarity is about 350ms when no dataflow on the bus. AZRS5485E detects the polarity real-time after power-on.

## **Application Circuit for Slave-Side Device (Polarity Free)**

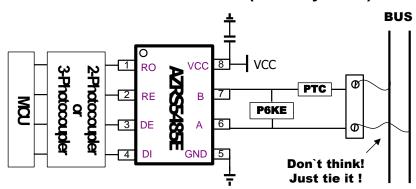


Fig. 13 AZRS5485E on the slave-side does not design the pull-up and pull-down resistor to form the polarity free function.



## **Application Circuit for Master-Side Device (Define Polarity)**

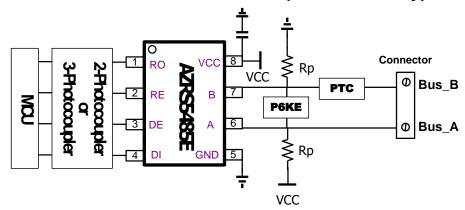


Fig. 14 AZRS5485E on the master-side to define which is Bus\_A and Bus\_B by pull-up and pull-down resistor, Rp.

The polarity free function of the AZRS5485E on the slave-side will be enable when the RS485 is under DE=REB=0V. Moreover, the pull-up and pull-down resistor, Rp, must not be designed on the device to define which is A or B, as show in Fig. 13. Once the polarity free conditions are ready, the operator can tie any pin to the bus. It is not necessary to know "which is A or B".

On the master-side design, the pull-up and pull-down resistors are necessary to define A or B on the RS485 bus. The pull-up resistor defines pin A to tie to Vcc and the pull-down resistor defines pin B to tie to GND. The master device defines the polarity for bus, which is BUS\_A and BUS\_B, as shown in Fig.14.

AZRS5485E can communicate with MCU through either 2-photocoupler or 3-photocoupler base.

The best design for Rp on master device is  $680\Omega$  for 2-photocoupler topology to connect below 50 slave devices. To connect more than 100 slave devices, the resistance of the Rp should be reduced to  $200\Omega$ , for example, which depends on the parasitic effect for the bus condition.

## Description for High-C<sub>AB</sub>-Loading driving Capability

The AZRS85E can handle high capacitive loading between bus A and bus B when long bus condition or protected device connected. In 2-photocoupler topology(DI always keeps low), the driver doesn't go into OFF immediately when logic level of DE goes from high to low. Driver keeps ON and drags  $T_{DD}$  time at least **8 us**, as showed Fig 15. In state 1, BUS\_A is fast changing from low to high and BUS\_B is quick from high to low(output of driver drives high in 8us). In state 2, the driver is OFF. BUS\_A is keeps high by pull-up resistor and BUS\_B is keeps low by pull-down resistor.

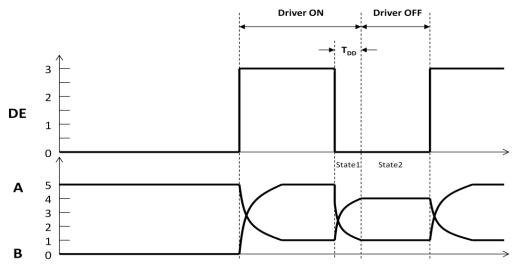
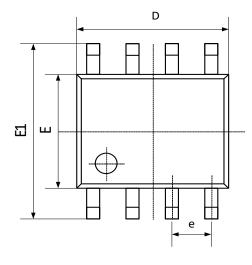


Fig. 15 The Timing of Driver On Drag (T<sub>DD</sub>) in 2 Photocoupler Topology

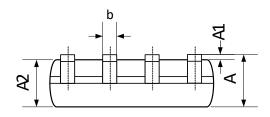


## **Mechanical Details**

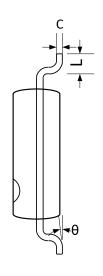
SO-8
PACKAGE DIAGRAMS
TOP VIEW



#### **SIDE VIEW**



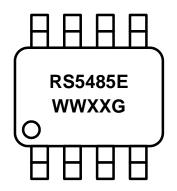
#### **END VIEW**



#### **PACKAGE DIMENSIONS**

	Millim	eters	Inc	hes
Symbol	min	Max	min	max
Α	1.35	1.75	0.053	0.069
A1	0.10	0.25	0.004	0.010
A2	1.25	1.55	0.049	0.061
b	0.33	0.51	0.013	0.020
С	0.17	0.26	0.007	0.010
D	4.70	5.10	0.185	0.201
Е	3.70	4.10	0.146	0.161
E1	5.80	6.20	0.228	0.244
е	1.27	BSC	0.05BSC	
L	0.40	1.27	0.016	0.050
θ	0	8	0	8

## **MARKING CODE**



RS5485E = Device Code

WW = Date Code

XX = Control Code

G = Green Part Indication

Part Number	Marking Code
AZRS5485E.RDG	RS5485E
	WWXXG



**Ordering Information** 

PN#	Material	Type	Reel size	MOQ/interal box	MOQ/carton
AZRS5485E.RDG	Green	T/R	13 inch	1 reel=2,500/box	5 boxes=12,500/carton

# **Revision History**

Revision	Modification Description
Revision 2014/04/25	Preliminary Release.
Revision 2018/05/08	Formal Release.
Revision 2018/05/08	Adds High-C <sub>AB</sub> -Loading driving capability description
Revision 2021/03/30	Modified Marking Code and Ordering Information